

CS-200

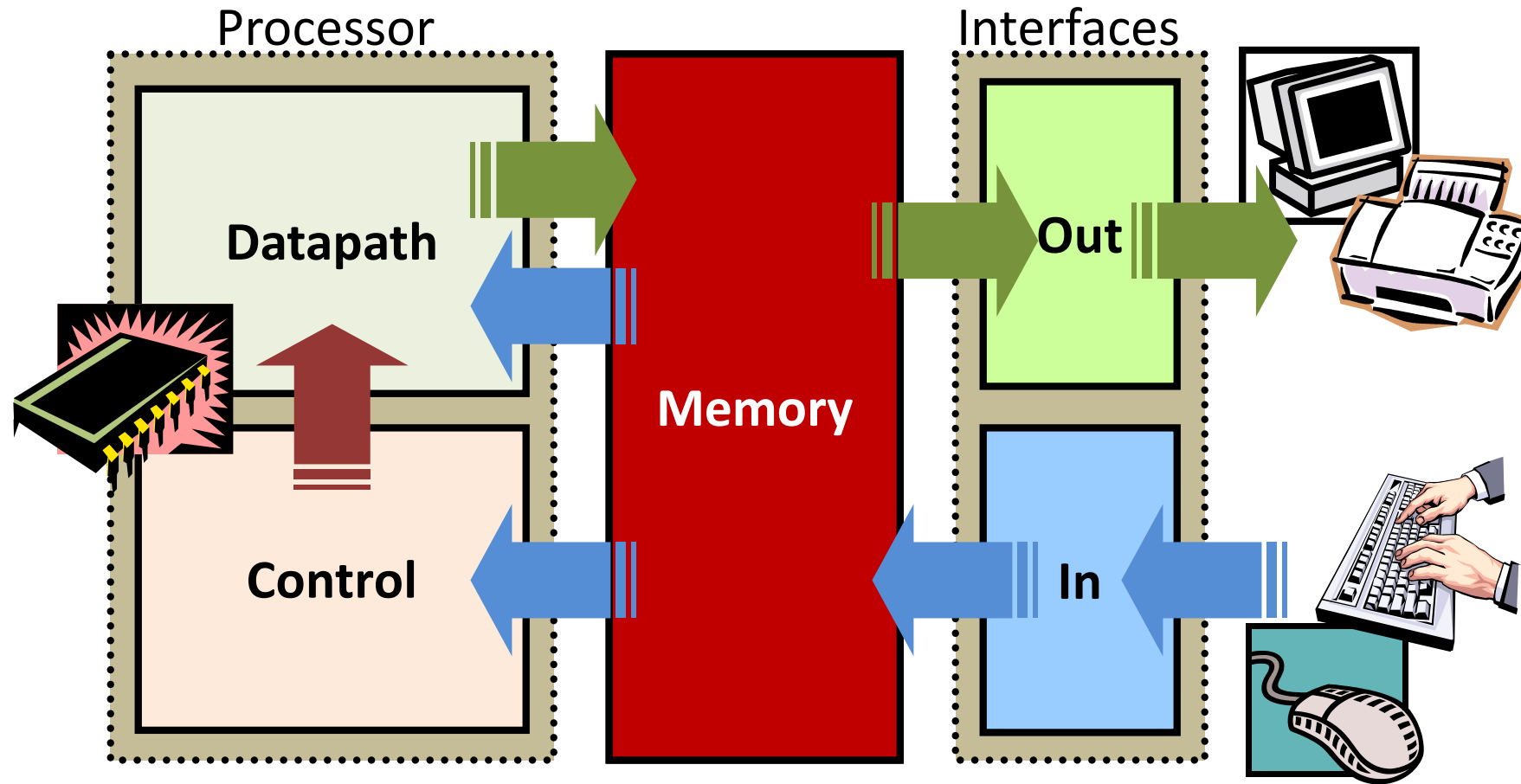
Computer Architecture

Part 2b. Processor, I/Os, and Exceptions

Inputs and Outputs

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The Five Classic Components of a Computer



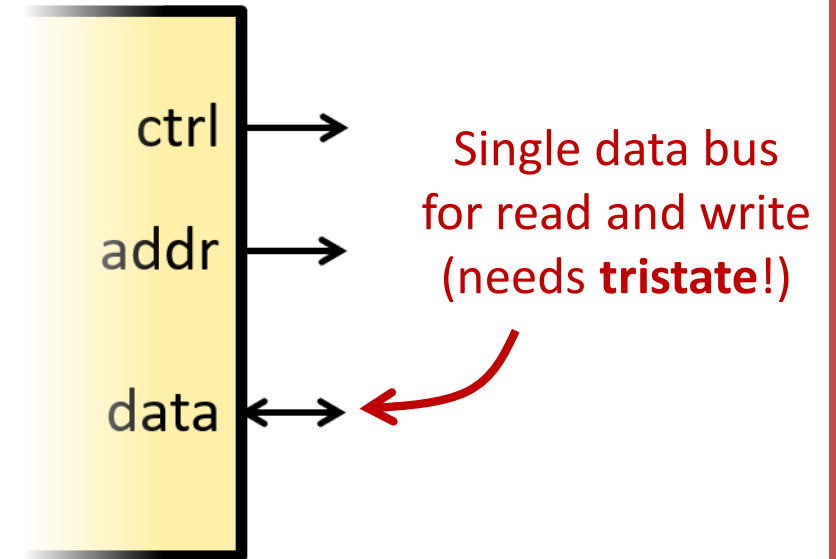
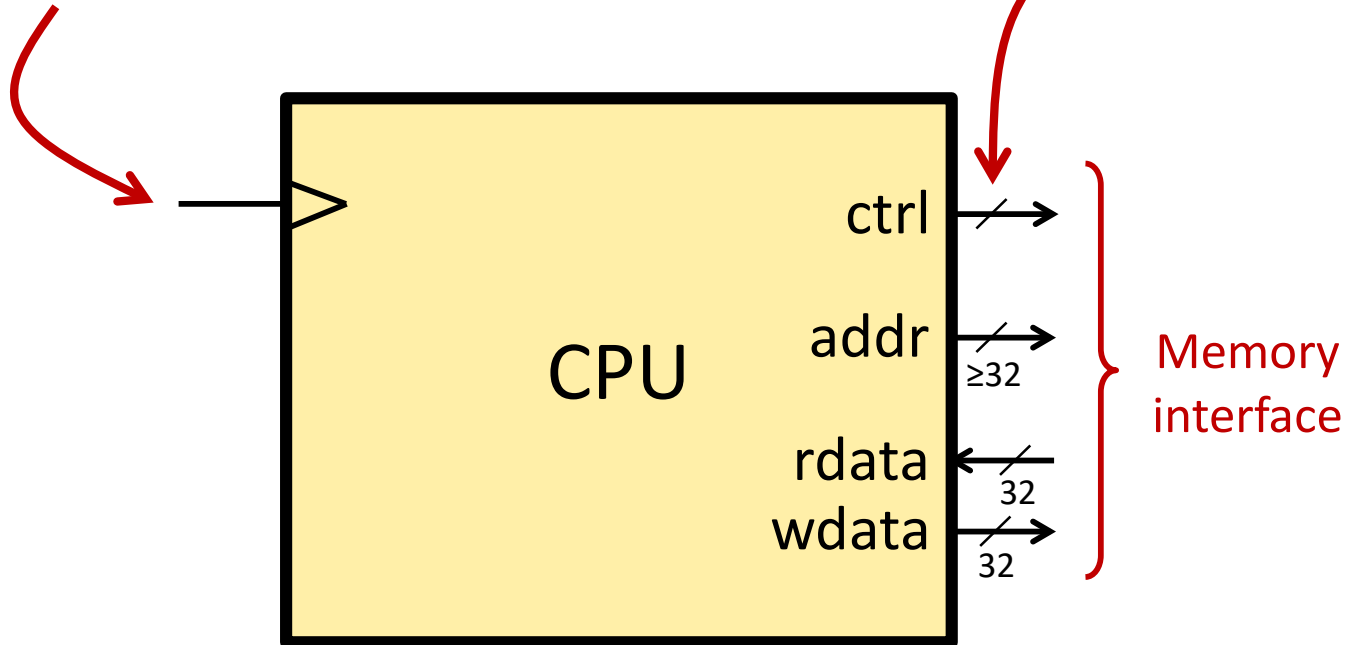
The CPU

A “very” **sequential** component
(but from now on we may
omit the **clock** in diagrams)

Signals like

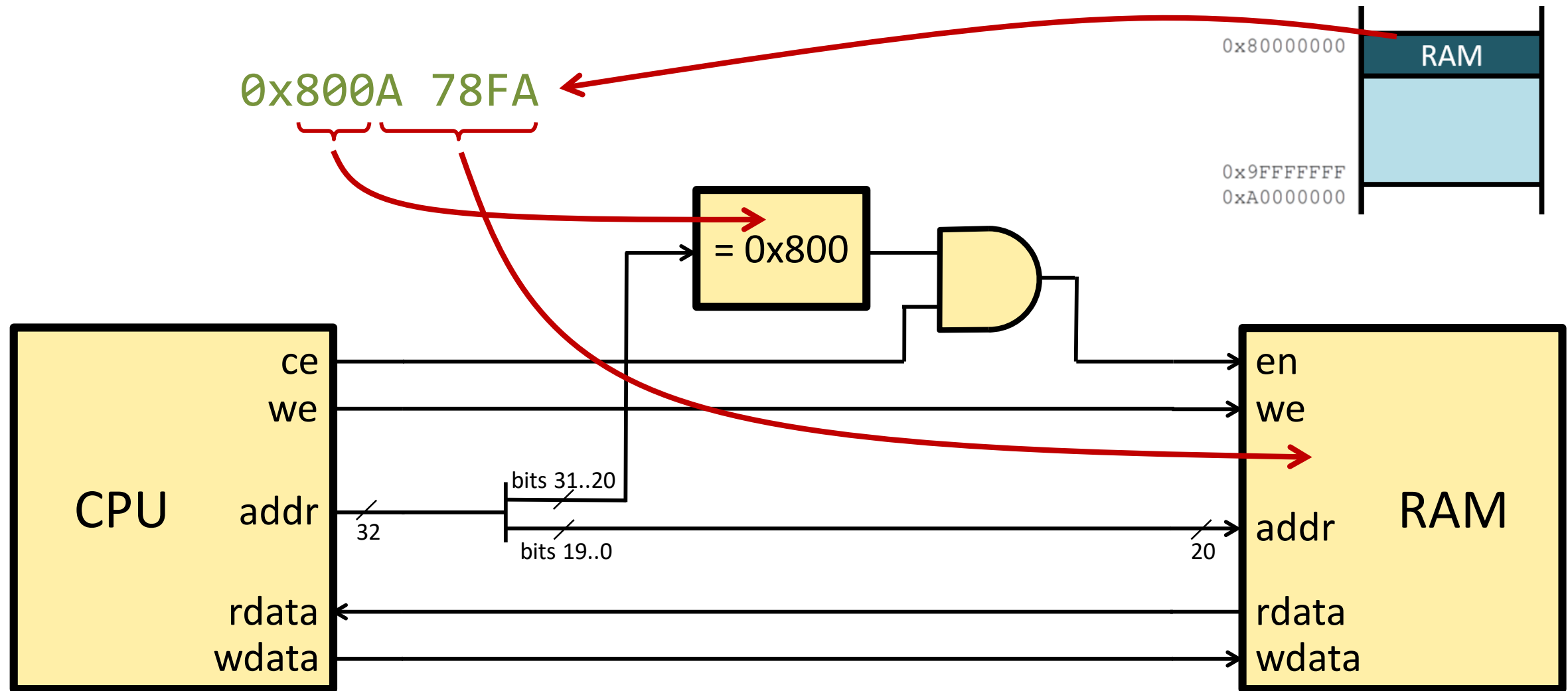
CE = Circuit Enable = address is valid

WE = Write Enable = access is a store

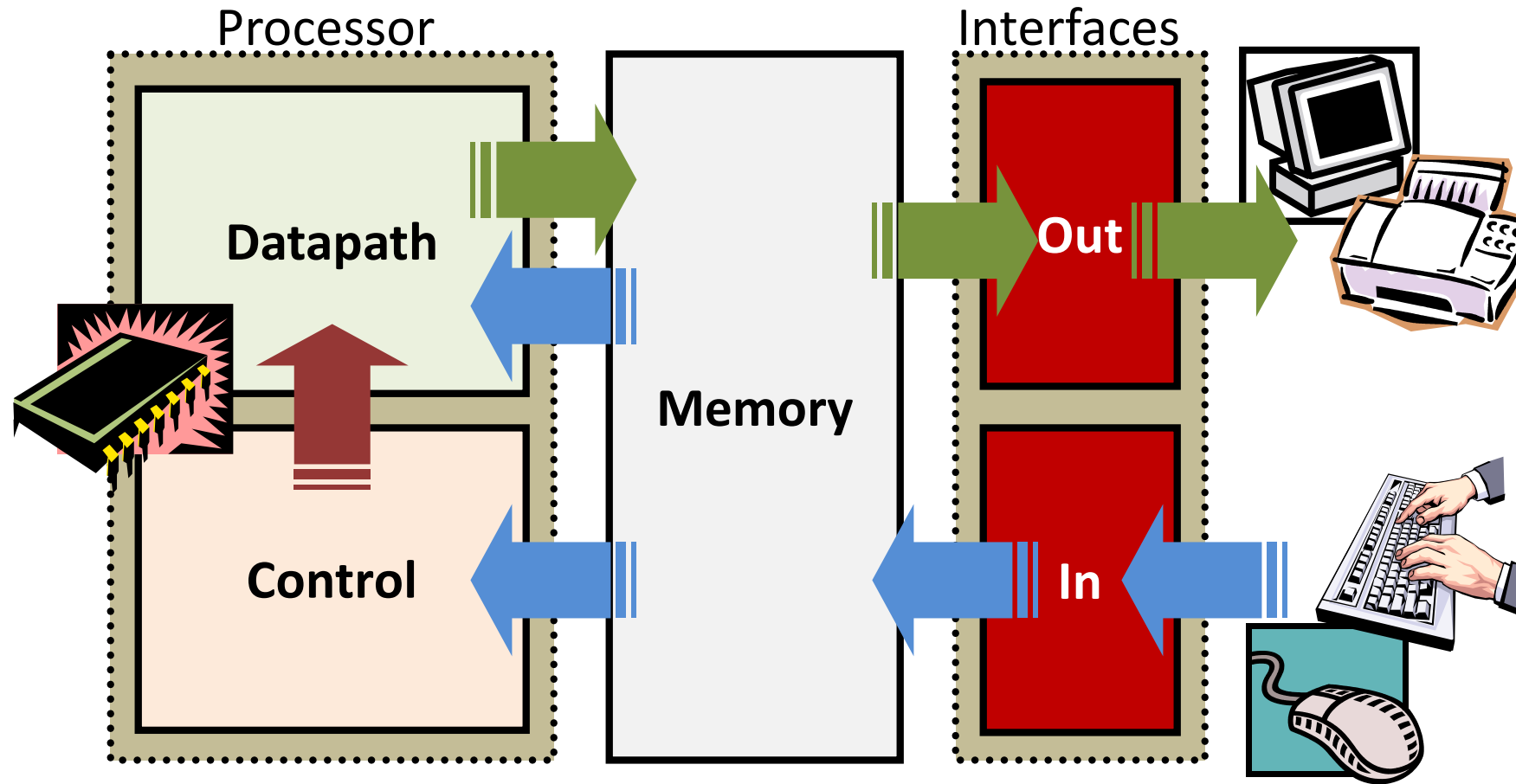




Connecting CPU and Memory



The Five Classic Components of a Computer

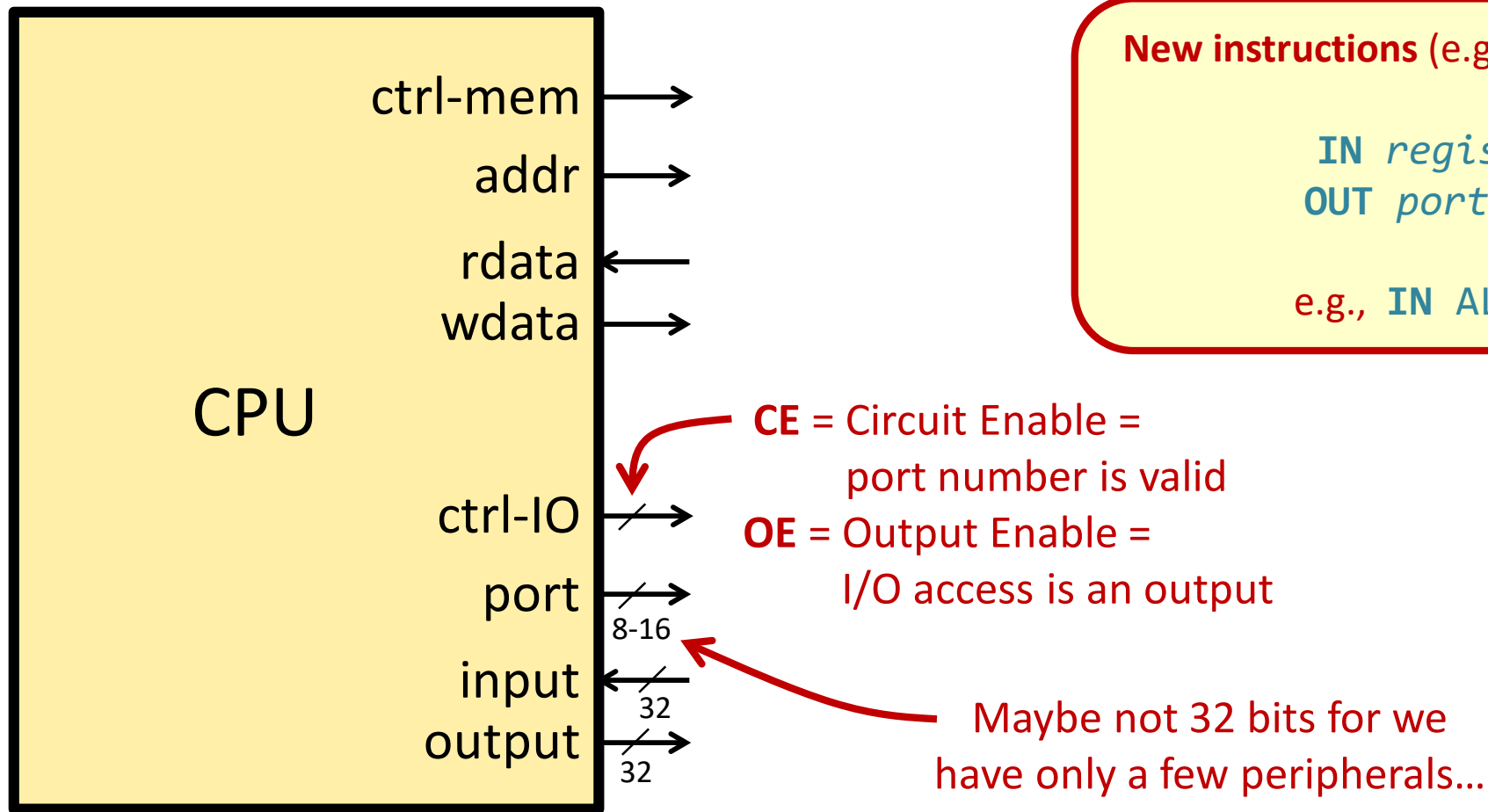


Input/Output Devices (I/Os)

Type	Peripheral	Data Rate
Human Interaction	Keyboard	~kbps
Human Interaction	Mouse	~kbps
Generic	Serial Port (RS-232)	115.2 kbps (max)
Generic	Parallel Port (LPT)	150 kbps
Generic	USB 4.0	20-40 Gbps
Generic	Bluetooth 5.0	2 Mbps
Generic	PCIe 4.0	16 Gbps per lane
Storage	SATA III (HDD/SSD)	6.0 Gbps
Storage	NVMe (PCIe 4.0)	64 Gbps (4-lane)
Networking	Ethernet (10BASE-T)	10 Mbps
Networking	10 Gigabit Ethernet (10GBASE-T)	10 Gbps
Networking	Wi-Fi 6 (802.11ax)	Up to 9.6 Gbps
Displays	VGA (analog video)	0.6-1.5 Gbps (approx.)
Displays	HDMI 2.1	48 Gbps
Optical Discs	CD-ROM	150 KB/s (1x) - 7.68 MB/s (52x)
Optical Discs	DVD-ROM	1.32 MB/s (1x) - 21.1 MB/s (16x)
Optical Discs	Blu-ray	4.5 MB/s (1x) - 54 MB/s (12x)

Accessing I/Os: Port Mapped I/O (PMIO)

- Create a **new interface** similar to the memory one

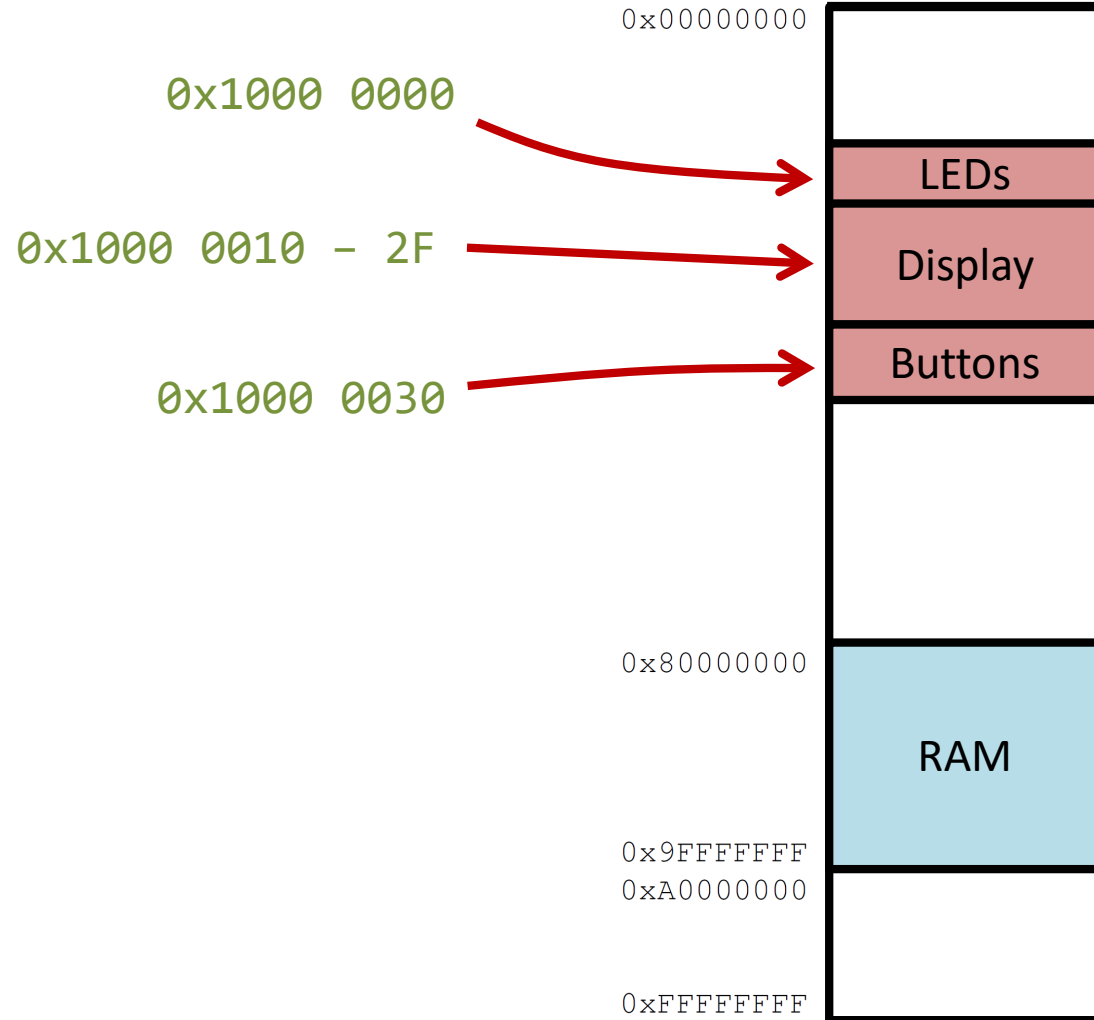


New instructions (e.g., x86 but seldom used):

IN register, port
OUT port, register

e.g., *IN AL, keyboard*

Accessing I/Os: Memory Mapped I/O (MMIO)

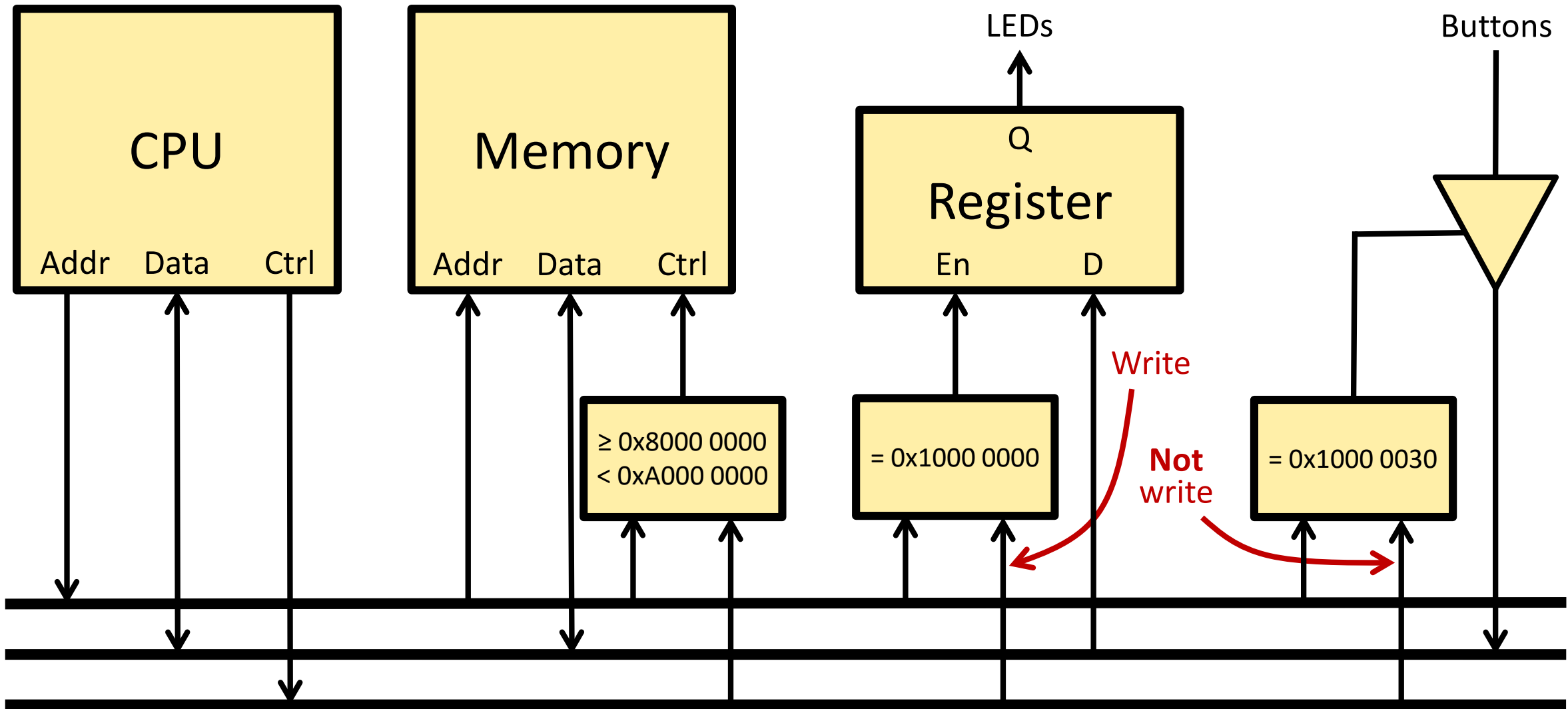


No special hardware needed in the CPU

No special instructions needed:

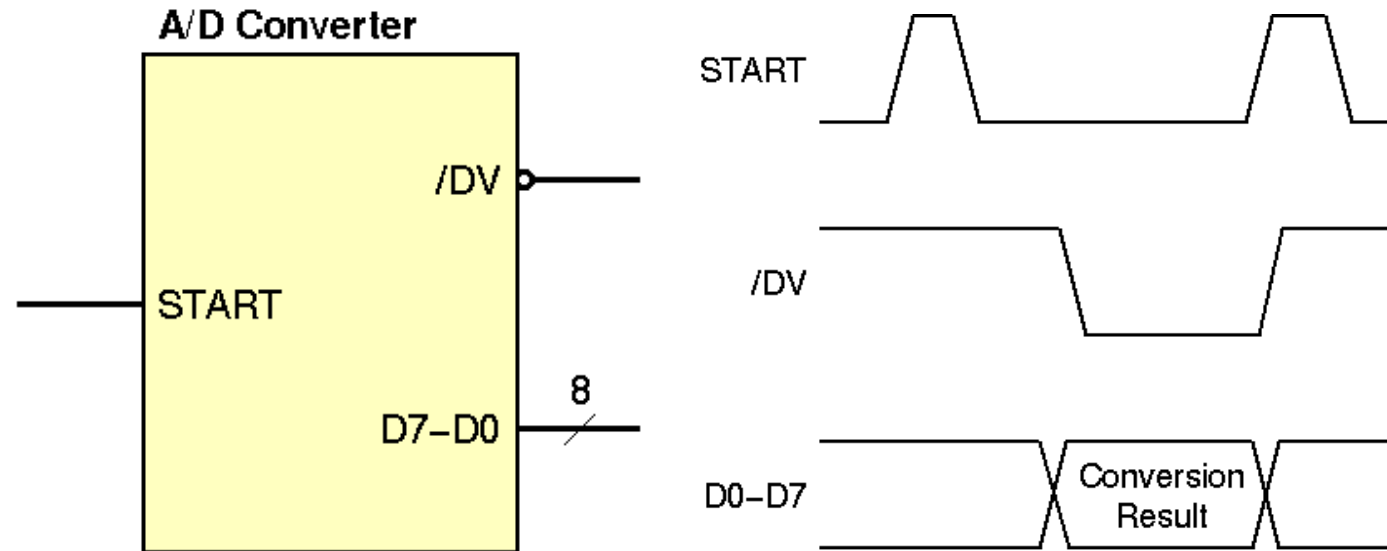
```
lui    t0, 0x10000    # pointer to I/Os
sw      t1, 0(t0)      # write LEDs
lw      t2, 0x30(t0)   # read buttons
```

Accessing I/Os: Memory Mapped I/O (MMIO)



Example: A/D Converter

- Signals:
 - **Start** (START): input; when active begins a new conversion
 - **Data Valid** (/DV): output; when active, D7—D0 are valid
 - **Data** (D7—D0): output; last conversion result



Example:

Simple Bus Interface

- Suppose that a 8-bit processor has the following signals:
 - **Address** (A23—A0): output; address bus
 - **Data** (D7—D0): input/output; data bus
 - **Address Strobe** (/AS): output; signals the presence of a valid address on the Address bus during a memory access cycle
 - **Read/Write** (R//W): output; signal the direction of the data flow
 - **Data Acknowledge** (/DTACK): input; must be activated at the end of a memory access, when the written data have been latched or the read data are ready
- Similar but not identical to the MC68000
- Just an example but already more complex than busses described so far (/DTACK)

Example:

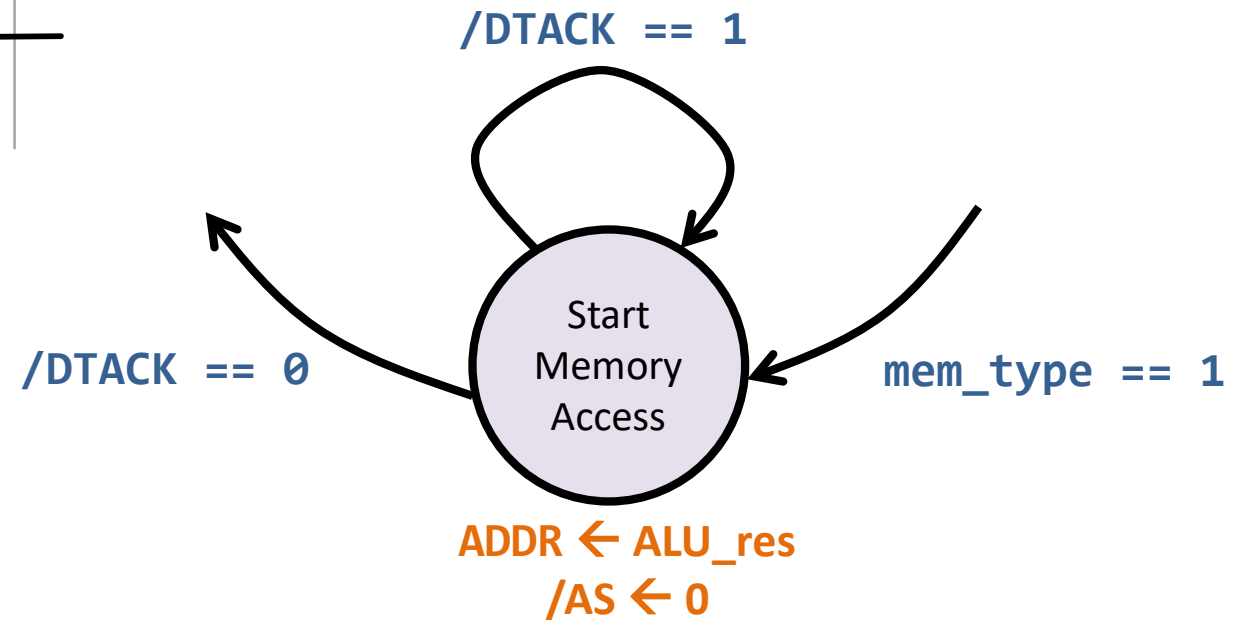
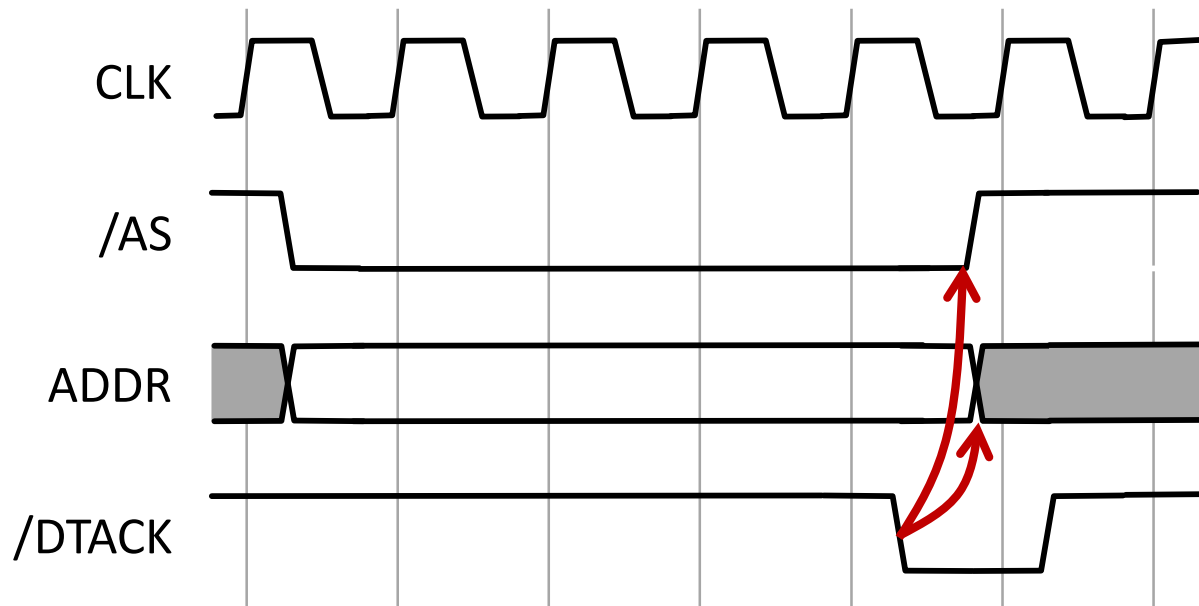
Memory-Mapped Interface

- Connect the A/D converter described in the previous slide so that:
 - **Any access** (R or W) to address **0xFFFF0** starts a **new conversion**
 - The **Data Valid** signal can be read by the processor at address **0xFFFF4** (bit 0)
 - The **result of the conversion** can be read by the processor at address **0xFFFF8**

What does /DTAC mean?

Circuit

What Does /DTACK Mean?





Software

A/D Converter: Software

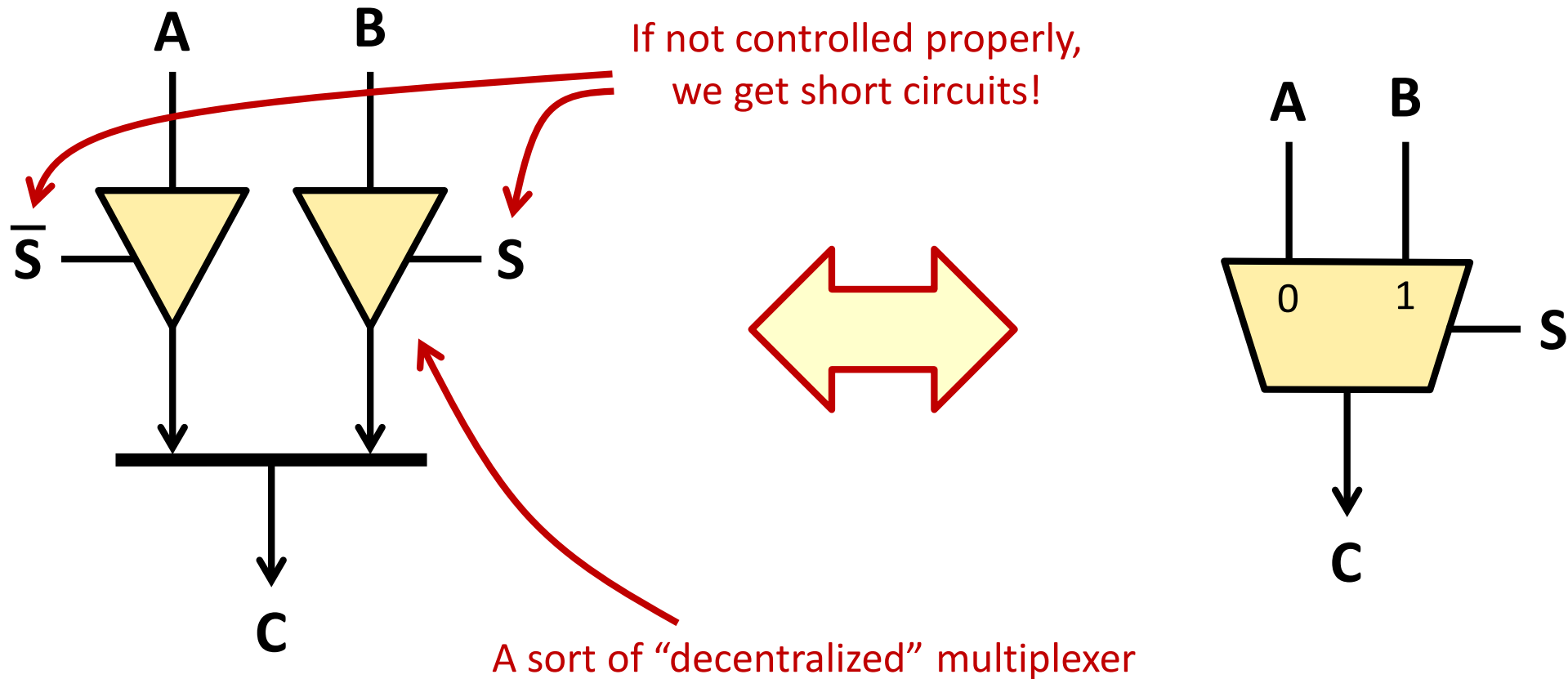
```
read_adc:    lui    t1, 0xffff
             addi   t1, t1, 0xff0      # t1 = 0xfffff0
             sw     zero, 0(t1)        # start conversion

poll:        lw     t0, 4(t1)          # t0 = DV signal
             beqz   t0, poll           # wait until done

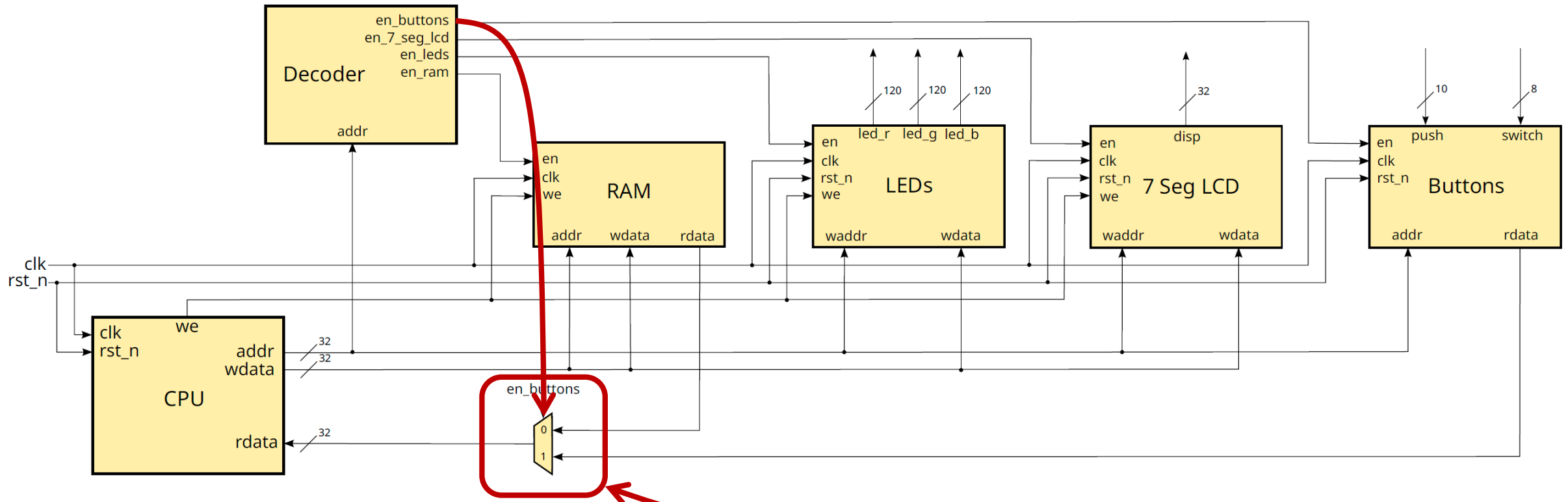
end:         lw     a0, 8(t1)          # a0 = A/D output
             ret
```

What Do These Tristate Buffers Do?

- What is their **logic function**?



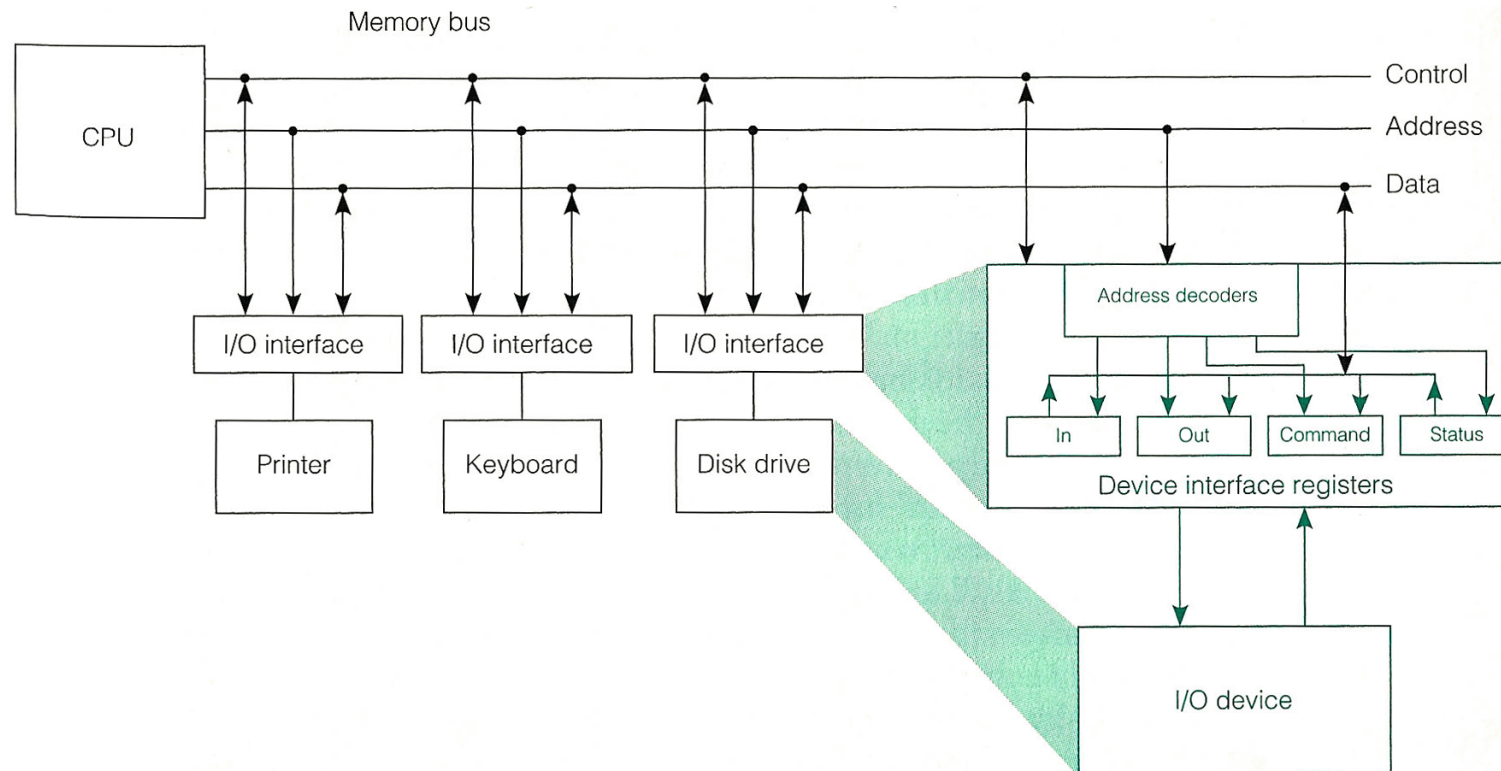
Your System in Lab B



Exactly the same function as the tristate buffers in the previous example

Programmed I/Os

Many peripherals are more developed programmable systems and have a set of registers which the processor reads and writes (a) to **send** and **receive data** and (b) to **issue commands** and **read the status**



A Classic UART

- **UART** = Universal Asynchronous Receiver-Transmitter
- One of the **simplest and most common communication** peripherals, typically used today to connect terminals to embedded devices
- Our UART has a **simple programmed I/O interface** with four registers:
 - A **control register** for the processor to configure the UART
 - Bit 7 must be set to 1 for the UART to be enabled
 - Bits 2..0 configure the communication speed (e.g., `0b001` for 9600 baud)
 - A **status register** for the processor to check the status of the UART
 - Bit 1 is 1 if there are data available
 - Bit 0 is 1 if the UART is ready to send data
 - A **data input** register where the received data are available to the processor
 - A **data output** register where the processor places data to send

A Classic UART

```
UART_CTRL_ADDR    = 0x10000000 # UART status register address
UART_ENABLE_BIT    = 0x80      # Enable bit (bit 7)
UART_SPEED_9600    = 0x01      # Speed setting for 9600 baud (4 bits, [3:0])
UART_STATUS_ADDR   = 0x10000004 # UART status register address
TX_READY_BIT       = 0x01      # Transmitter ready bit (bit 0)
UART_DATAIN_ADDR   = 0x10000008 # UART data input (receive) register address
UART_DATAOUT_ADDR  = 0x1000000C # UART data output (send) register address
```

Configure and enable the UART

send_string:

```
li t0, UART_CTRL_ADDR # Get UART control address
li t1, UART_STATUS_ADDR # Get UART status address
li t2, UART_DATAOUT_ADDR # Get UART data address
li t3, UART_ENABLE_BIT # Get enable bit (0x80)
li t4, UART_SPEED_9600 # Get speed setting (0x01)
or t4, t3, t4 # Combine enable and speed bits
sw t4, 0(t0) # Configure using the UART control register
```

Wait until we can send
a new character...

next_char:

```
lb t5, 0(a0) # Load first byte of the string
beqz t5, finish # If byte is zero (null terminator), finish
```

...and send it

check_tx_ready:

```
lw t6, 0(t1) # Load UART status register
andi t6, t6, TX_READY_BIT # Check if TX_READY_BIT is set
beqz t6, check_tx_ready # If not ready, loop back and check again
```

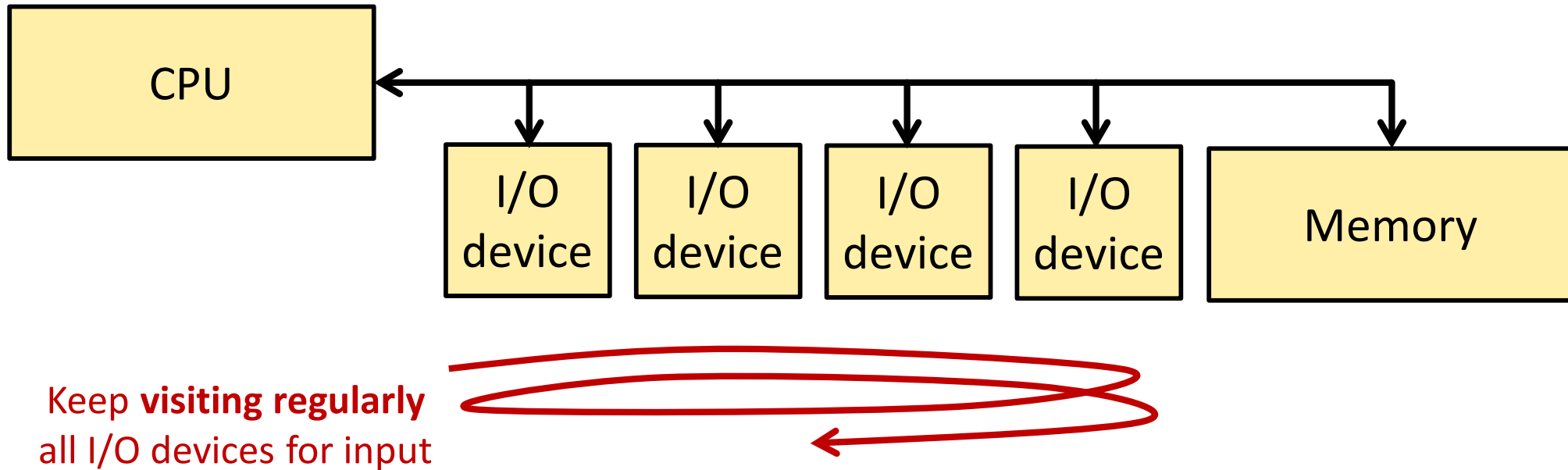
```
sw t5, 0(t2) # Store the character in UART data register
addi a0, a0, 1 # Increment string pointer (move to next char)
j next_char # Jump back to send the next character
```

finish:

```
ret # Return when the string is done
```


I/O Polling

- How do we know if **a peripheral has data** for us (key pressed, packet arrived, etc.)?



- Very expensive:** if the device is fast and requires immediate action, the processor must spend too much time to check **frequently**